



FIG WORKING WEEK 2023

28 May - 1 June 2023 Orlando Florida USA

Protecting
Our World,
Conquering
New Frontiers

TOPIC: APPLICATIONS OF LIDAR IN ENGINEERING GEODESY

Implementation and Optimization of a complete
process of Collection, Classification and
Exploitation of LIDAR data

- Audrey ALAJOUANINE, France
- Mohamed Khalil MASMUDI, Tunisia



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Summary

- General context
- Organization of the flight missions by UAV
- Classification of Lidar Point Cloud
- Exploitation of Lidar data
- Conclusion

General context : How can we optimize the process of collecting, processing and using LIDAR data?

Reduce the very high cost of map products generated from LIDAR data

Minimize the processing time of LIDAR point clouds

Avoiding manual processing of LIDAR data

- General context
- Organization of the flight missions
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General context

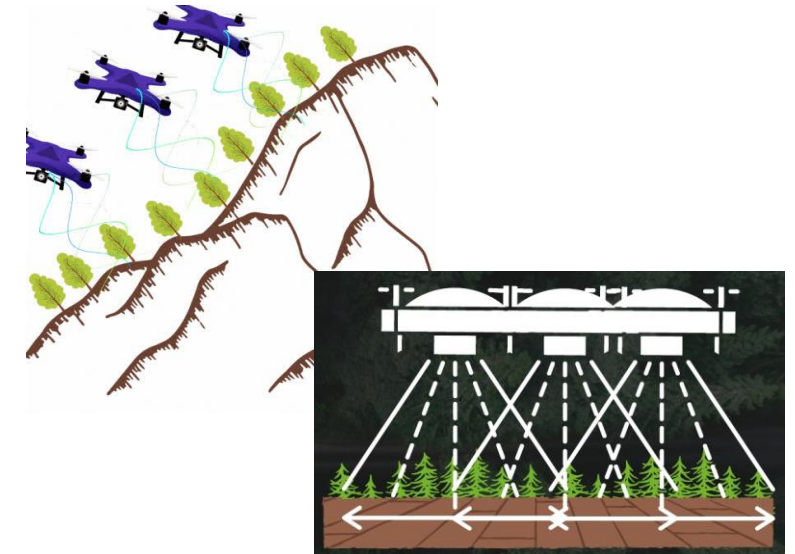
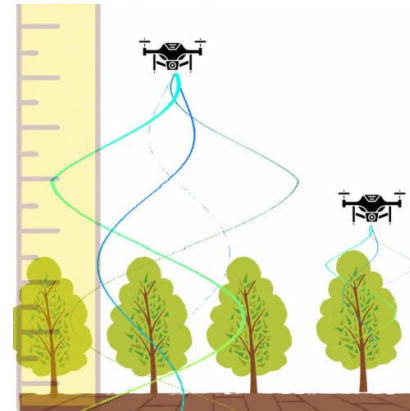
Improve and specify the flight mission organization parameters for each study area

Implementation of a classification process of LIDAR point clouds for each area according to land use

Optimize the methods of exploitation of LIDAR data

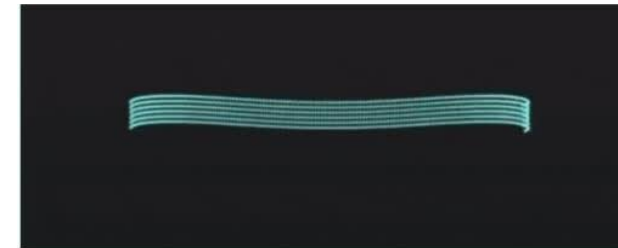
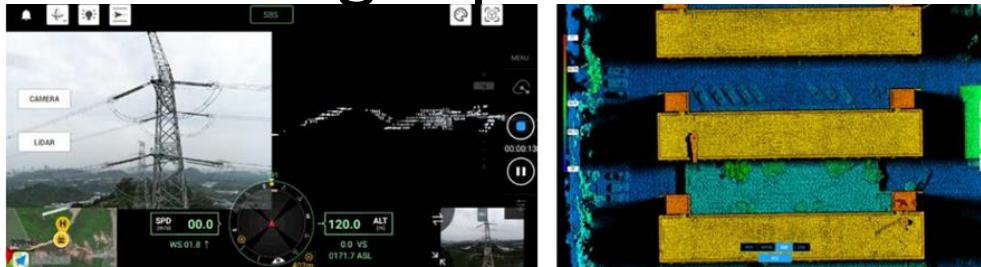
Organization of the flight missions : Define the parameters for the flight mission in each type of project

- Point Cloud density
- Flying height
- Terrain follow mode
- Speed
- Overlap
- Scanning mode

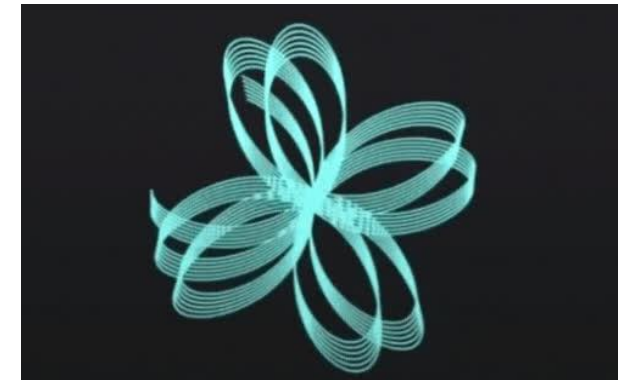
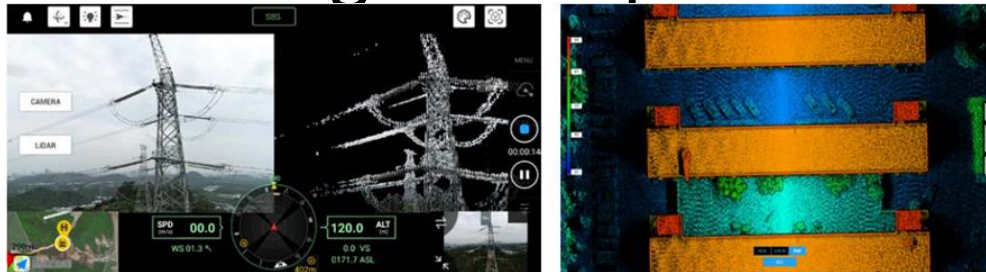


Organization of the flight missions : Define the parameters for the flight mission in each type of project

- Scanning repetitive mode



- Scanning non-repetitive mode



Classification of Lidar Point Cloud :

Create an automatic classification process of LIDAR point clouds on 5 study areas according to their characteristics

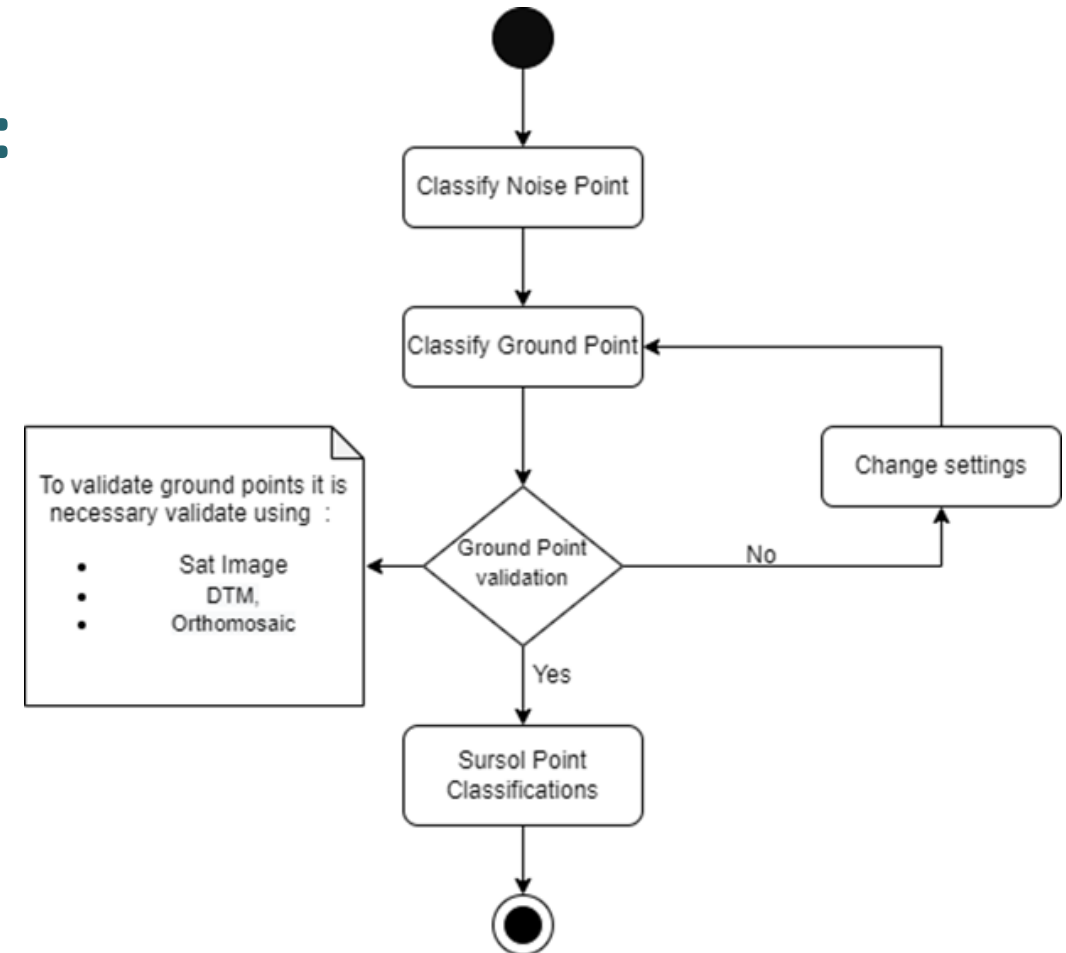
- Routines
- Extraction of parameters
- Macros



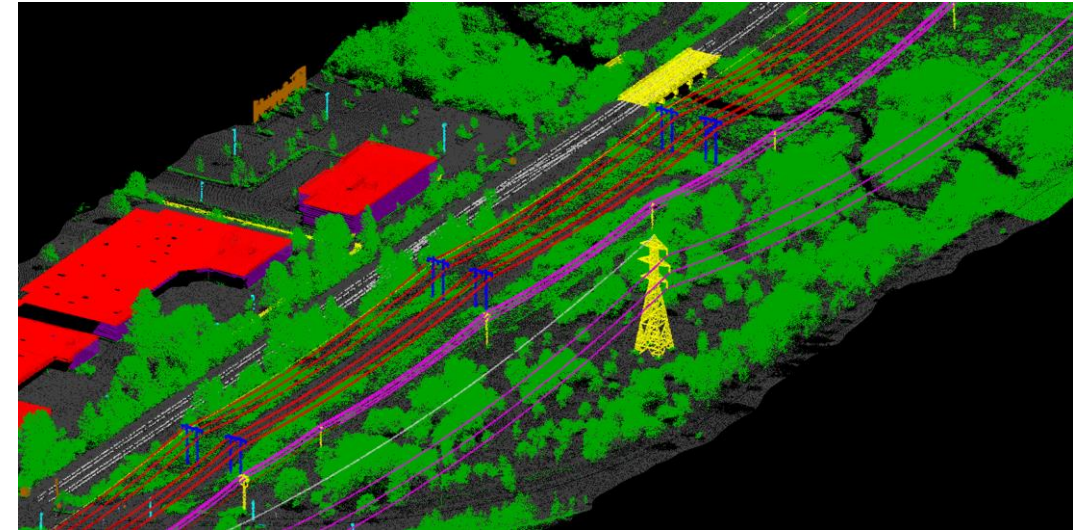
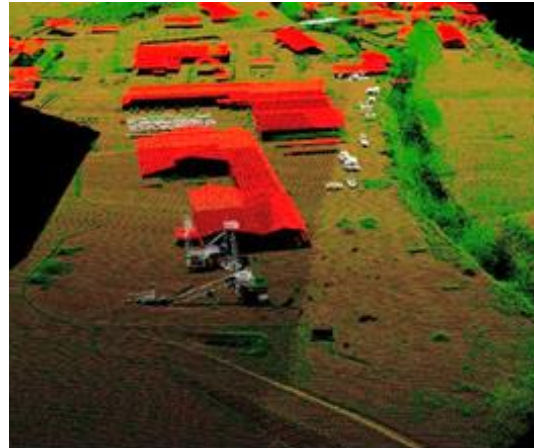
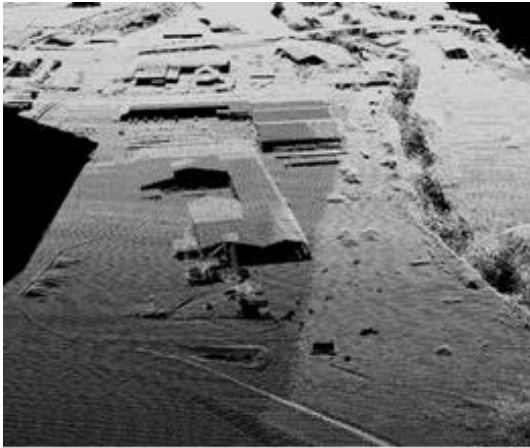
Rural area
Mountainous area
Urban area
Quarry area
Power lines

Classification of Lidar Point Cloud :

- Visualize in 3D the intense models, elevation model by color, model of colored points and representation of echoes to better understand the area and know the distribution of elements and details present in the area
- Calculate the necessary parameters for the routines: slope, building area, point density ...
- Create a processing macro to automate the process
- Manually reclassify the badly classified points

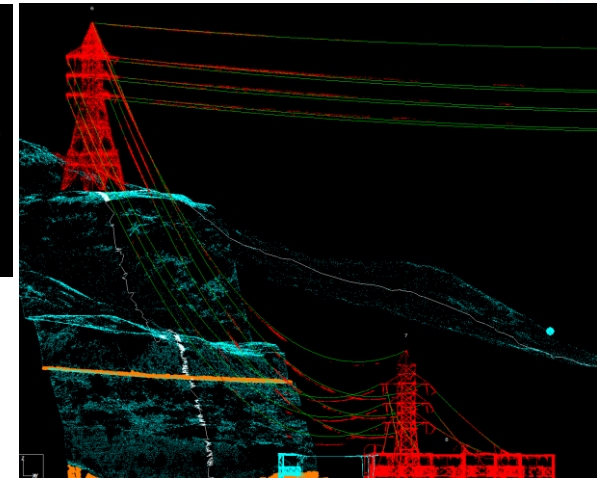
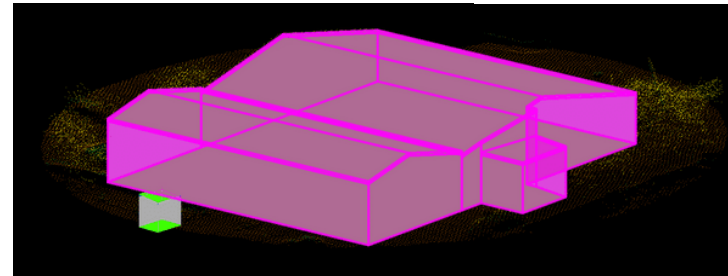
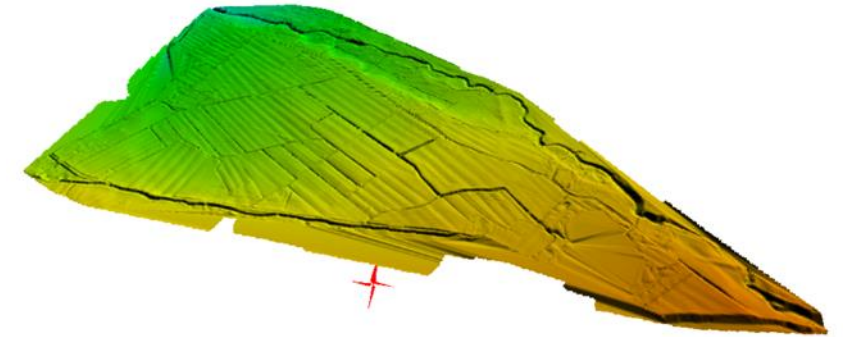
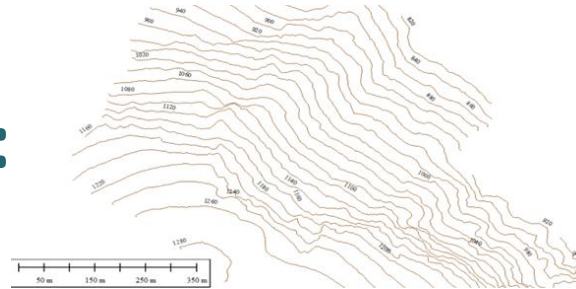


Classification of Lidar Point Cloud :



Exploitation of Lidar data :

- 3D cartographic product: DTM, DSM, contour line
- The generation of 3d vectors of constructions
- LIDAR data in several formats according to customer demand



Conclusion

4 data processing and exploitation softwares

300 GB of LIDAR data processed

100% automatic classification in most projects

validation by field data

Ground classification optimization in urban areas

Analysis and studies: Hydrography, Agriculture, Geological Risks

Automatic 3D vector generation at large scales



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